

# Theoretical Limits on Channel Assignment in Mobile Ad Hoc Networks

## MidTerm Progress Report

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# Outline

- 1 Introduction
  - Problem
  - Model
- 2 Theoretical Foundation
- 3 Bibliography

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# Mobile Ad Hoc Networks

## Definition (Ad Hoc Network)

A mobile ad hoc network is a peer to peer wireless network.

## Features

- Distributed routing
- All links are wireless
- Dynamic links between peers

## Issues

- Competition for resources
- Routing is specialized

# Structured MANET

We can simplify these issues if we can simplify the network.

## Goals

- 1 We minimize collisions between peers
- 2 We maximize network flow subject to (1)

## Features

We impose a structure on the MANET such that

- 1 Links between Nodes are bidirectional
- 2 Links exist on a subset of possible links
- 3 Links are persistent, but not permanent
- 4 Nodes are connected

Creating a structured network of mobile, wireless nodes would improve the performance of ad hoc networks.[2]

# Problems

## Structured Wireless Networks are worth building

A major assumption of this research is that there is something to be gained by imposing a structure on an ad hoc network.

Potential advantages include:

- improvements in battery life
- greater capacity

# Problems

## Initialization Problem

The wake-up problem confronts initialization of asynchronous nodes. That is, nodes in an ad-hoc network may wake up at different times. The initialization problem confronts joining nodes into a network in the absence of a global clock or an existing network structure.

## Channel Assignment Problem

A general problem in Ad Hoc Networking. A network is channelized when it only exploits some subset of its possible connections in such a way as to minimize collisions between messages.

# Representation of an Ad Hoc Network

## Unit Disk Graphs

An ad hoc network can be modeled as a unit disk graph, that is, a graph

$$G(V, E) \mid \forall e \in E, v_0, v_1 \in V, \exists e(v_0, v_1) \iff d(v_0, v_1) \leq 1$$

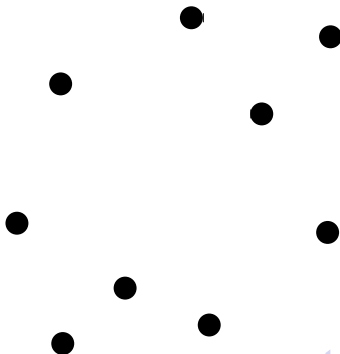
where  $d$  is the euclidean distance from  $v_0$  to  $v_1$ .

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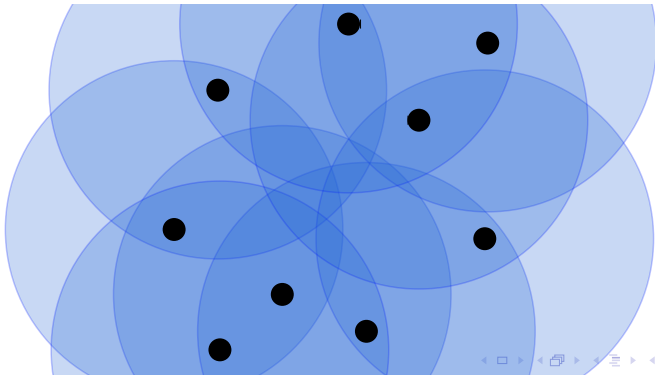


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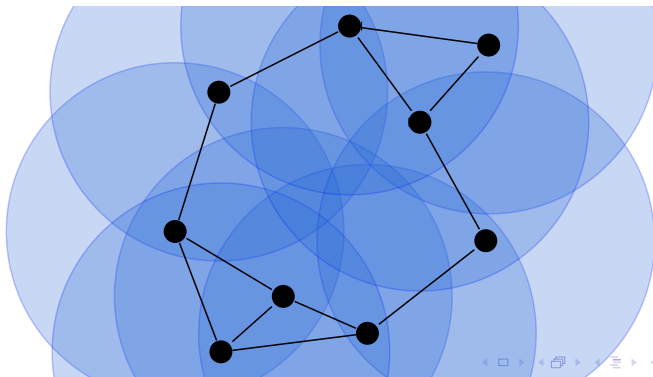


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# Operational Paradigms

This problem has been studied in several paradigms

- TDMA
- CDMA
- Multi-Radio Multihop (Mesh)

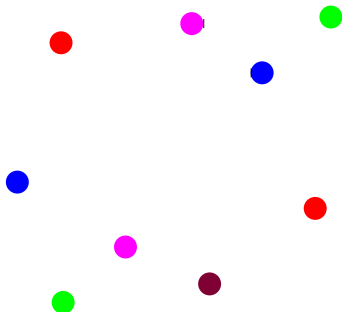
A paradigm agnostic analysis would be helpful

# Resource Division & Vertex Coloring

## Scheme

Resource Division is a general means of structuring an ad hoc network. In any RD scheme, nodes gain the right to utilize the resource.

- Each color represents a resource
  - resources are divided by color
  - conflict is avoided

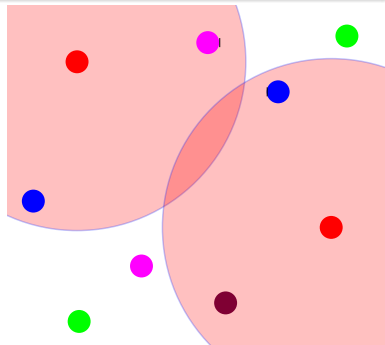


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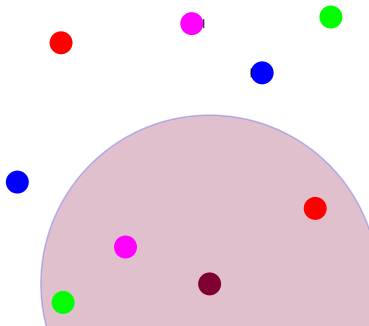


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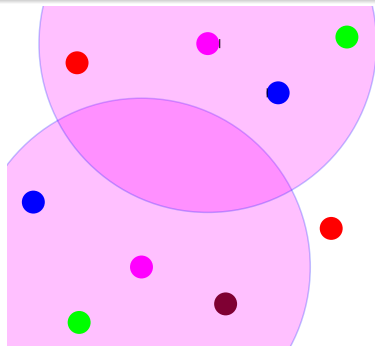


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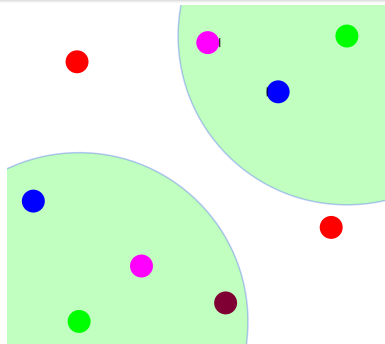


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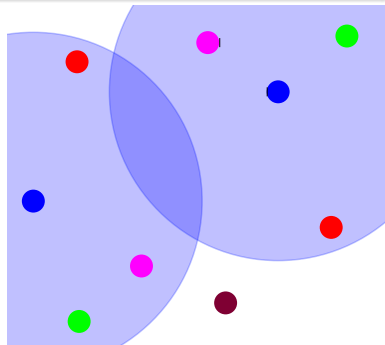


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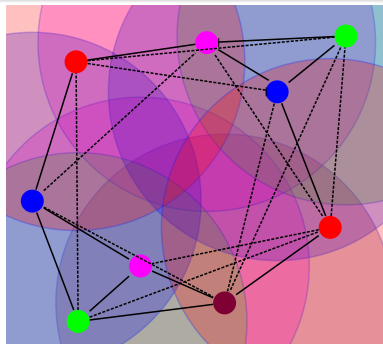


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- Must color the square of the graph

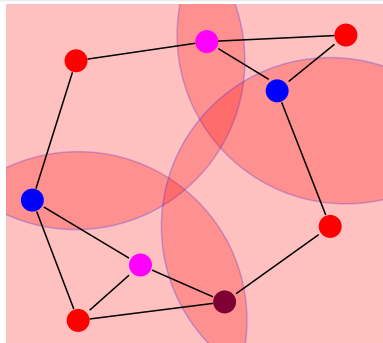


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- Must color the square of the graph
- Standard coloring allows conflict



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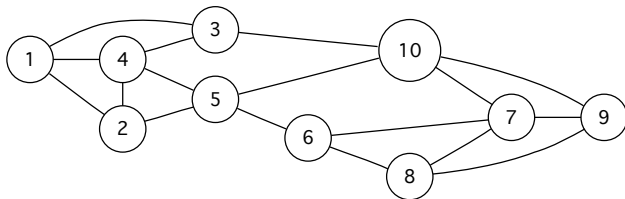
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# Prior Work

Avonts et. al[1] showed that this problem can be viewed as a graph coloring problem

- Unit Disk Graph  $G(V, E)$

Each network node is a vertex, and an edge exists if the nodes can communicate

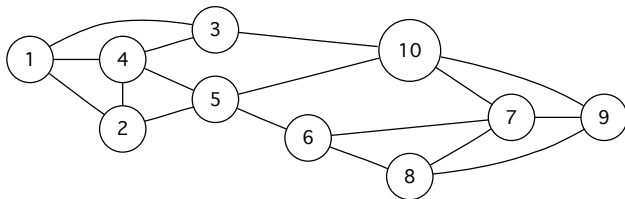


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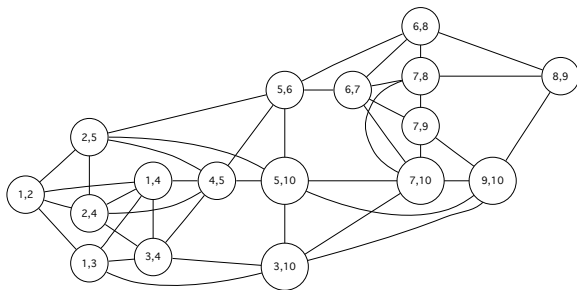
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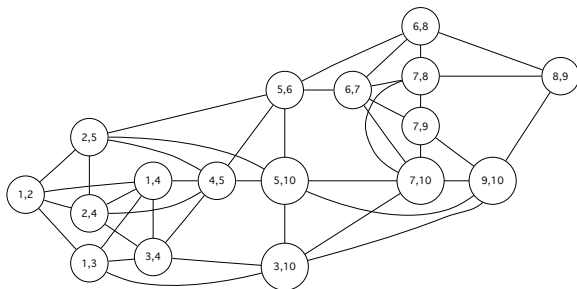
- Edge Conflict Graph  $C(G)$   
Each vertex represents a potential communication link, and edge exists if two links share a common network node



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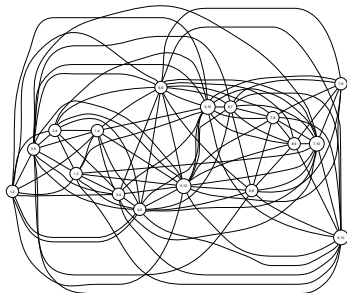
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Add edges between links that share a common neighbor in  $C(G)$



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- To solve: a vertex coloring on some selection of  $ECG^2$

# Open Formal Questions

This problem has been defined, but a rigorous analysis of the relationship between Graph Density, Graph Magnitude, and the number of required colors has not been established.

- 1 Given a density, can we predict the number of resources needed to structure the network?
- 2 Given some number of resources, can we predict the density and magnitude of the graph that can be colored
- 3 Can we predict the level of inevitable conflict, and does that inform our conflict resolution schemes?

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